

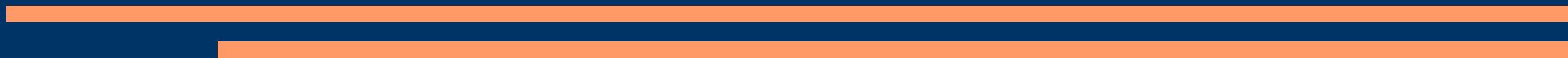
# *Recent activities with the ALADIN/HU 3DVAR system*

16<sup>th</sup> ALADIN workshop  
May 16-19 2006

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and  
Roger Randriamampianina

# *About...*

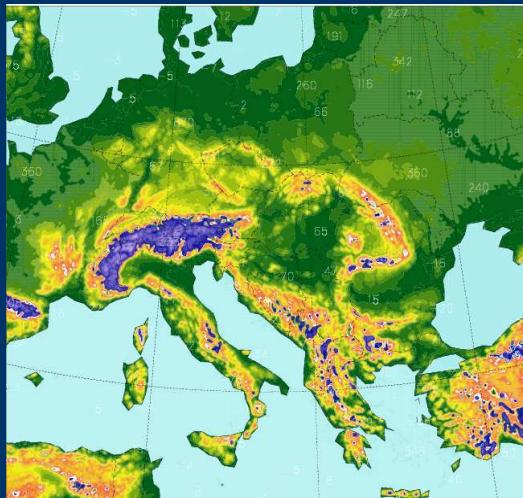
1. Operational changes
2. General performance
3. Recent developments
4. Plans



# *Operational changes*

## Main features:

- AL28T3
- 3DVAR assimilation
- 48h production (2/day)
- ARPEGE LBC



## Assimilation settings:

- 6h cycle
- short cut-off prod. analyses
- NMC method
- DFI
- LBC every 3 hours

(short cut-off ARPEGE files at 00 UTC)

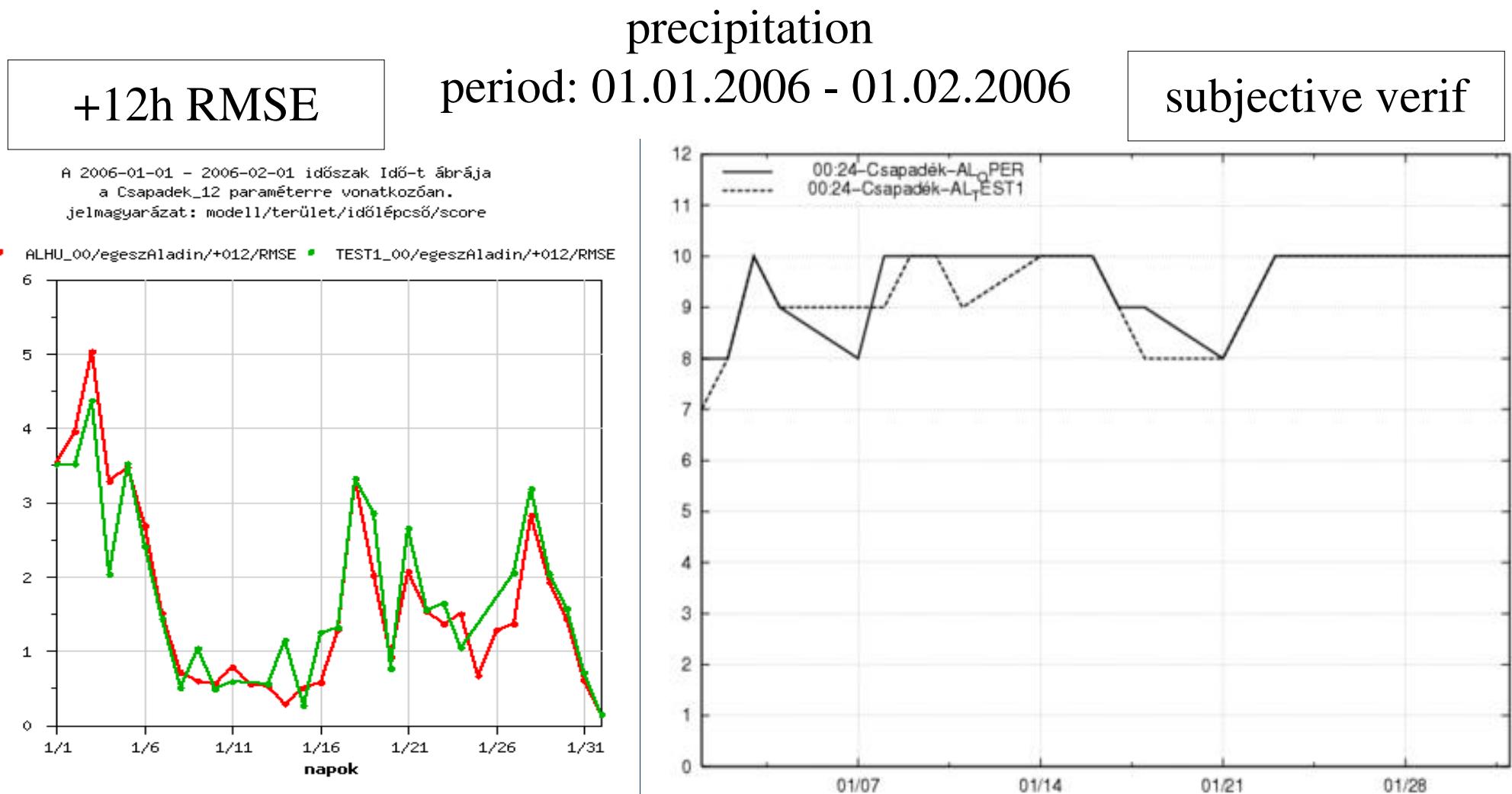
## Model geometry:

- $dx=8\text{km}$  ( $349*309$ )
- 49 levels
- linear grid
- Lambert projection

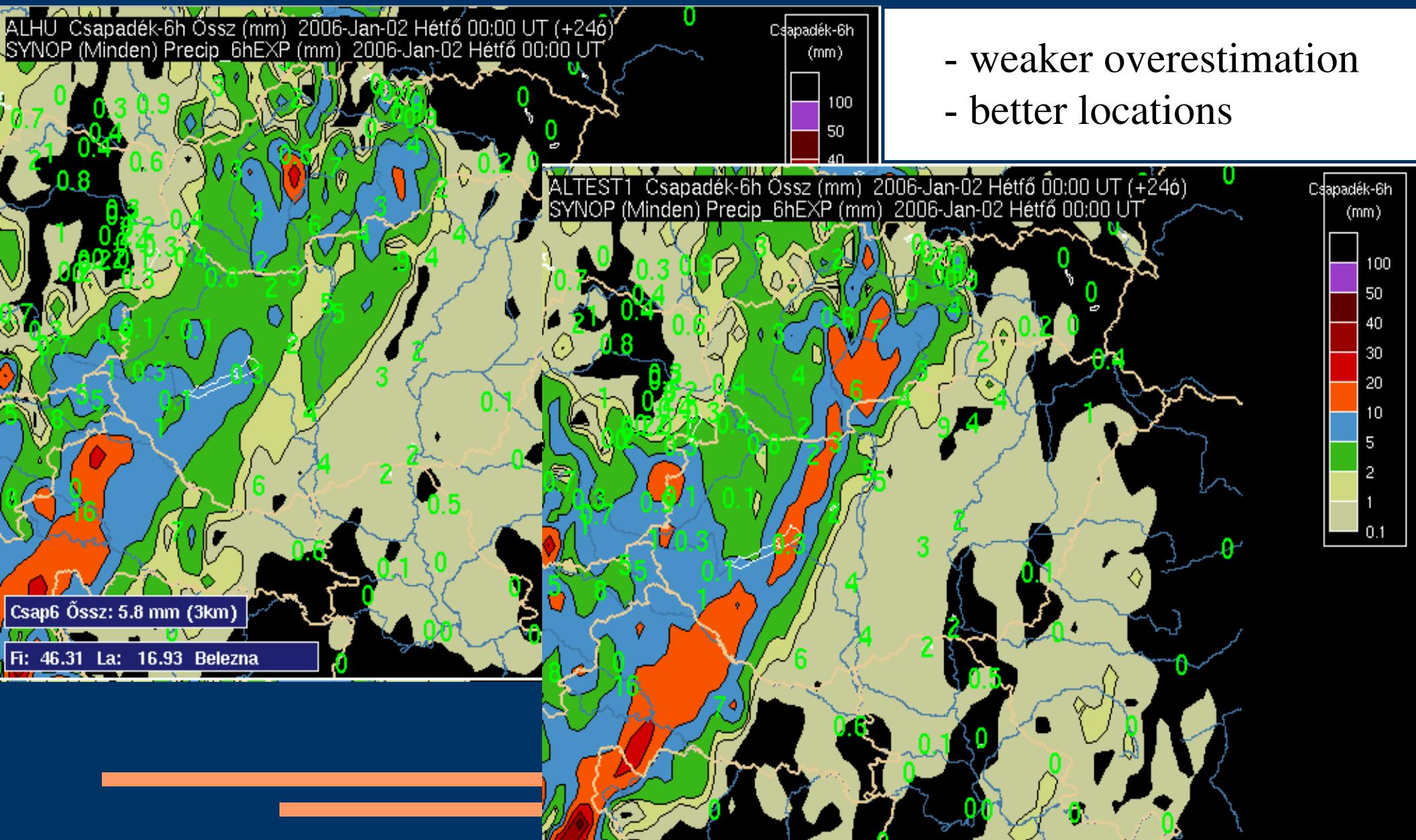
## Observation use:

- SYNOP, SHIP (geop)
- TEMP (T,u,v,q)
- ATOVS/AMSU-A
- ATOVS/AMSU-B
- AMDAR (T,u,v) + filter

# *Comparison with dynamical adaptation*

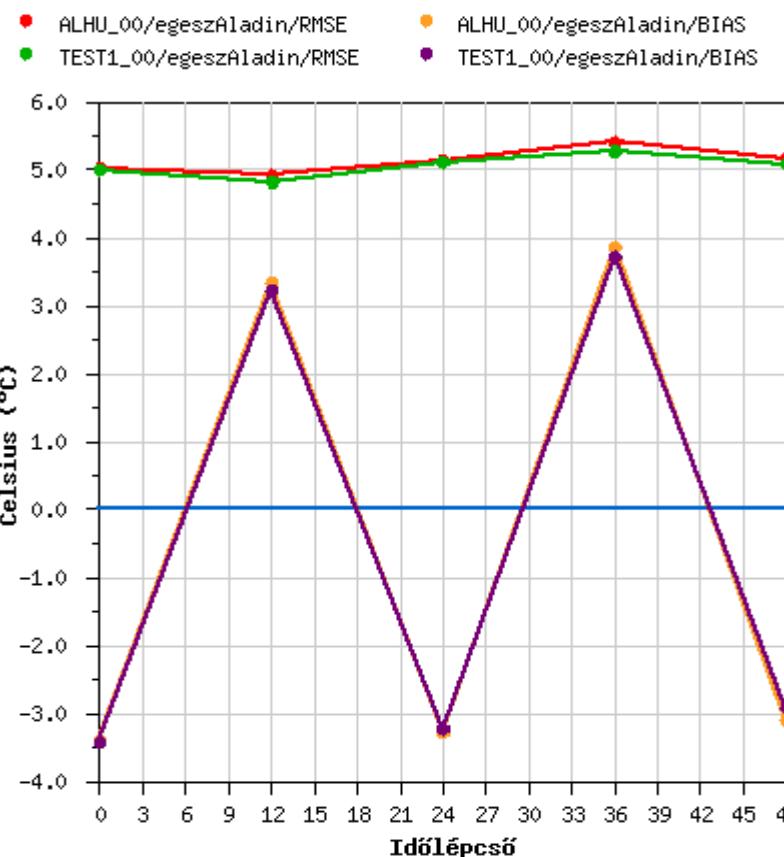


# *Comparison with dynamical adaptation*



# *Comparison with dynamical adaptation*

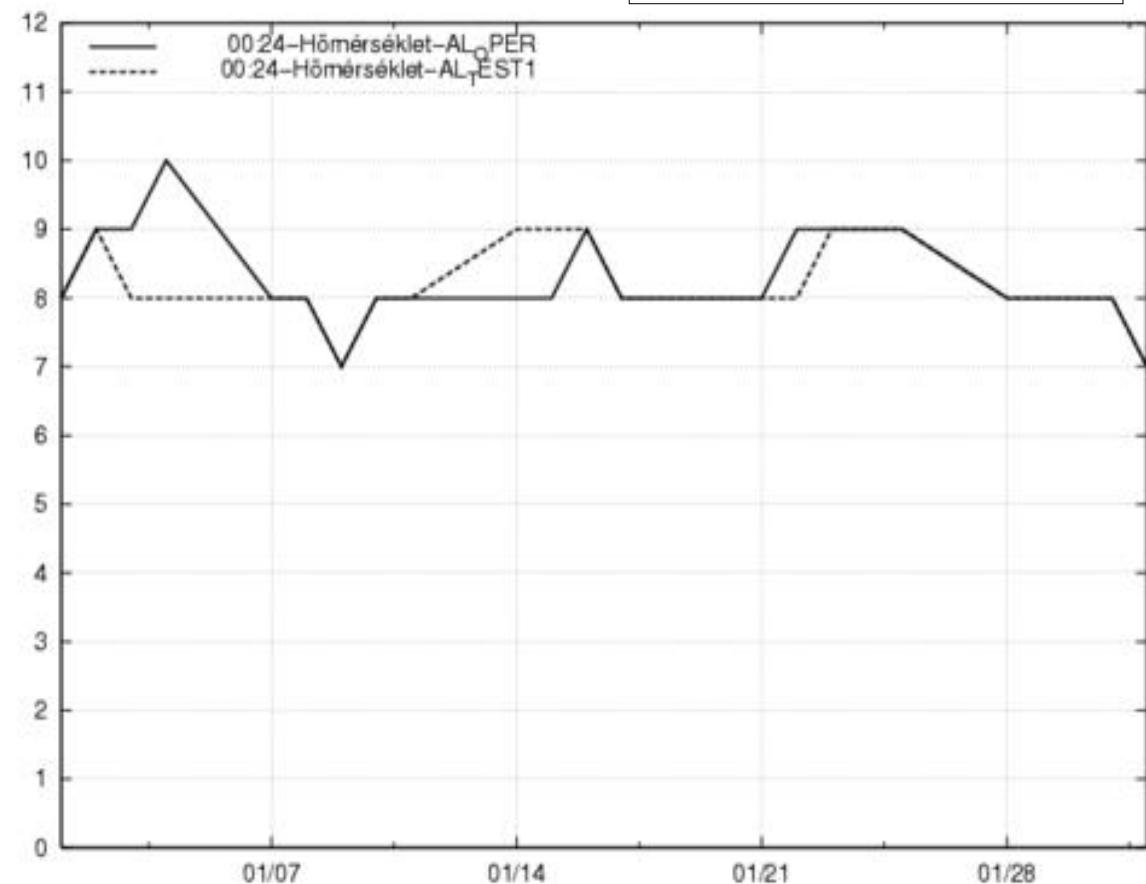
RMSE & BIAS



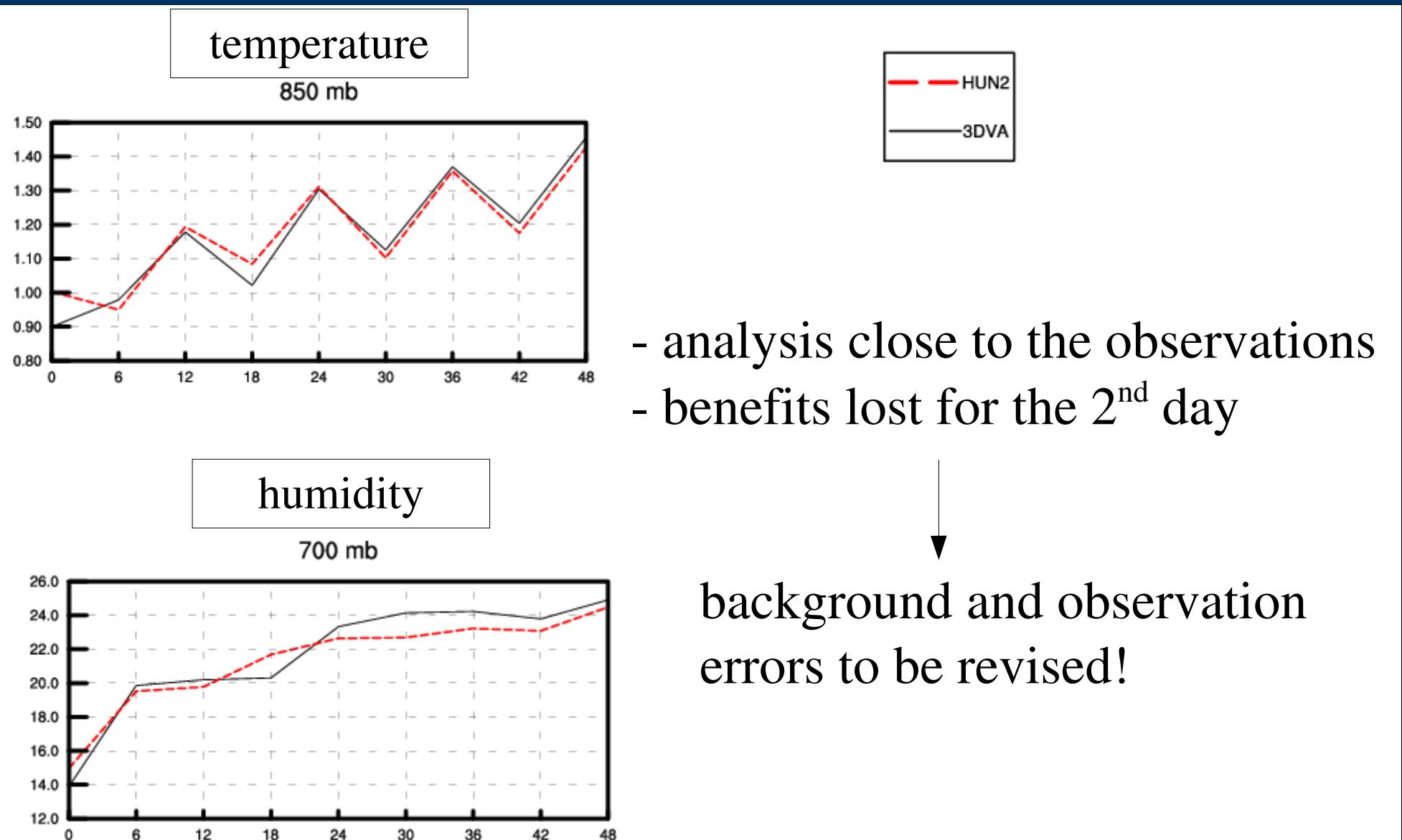
2m temperature

period: 01.01.2006 - 01.02.2006

subjective verif



# *Comparison with dynamical adaptation*

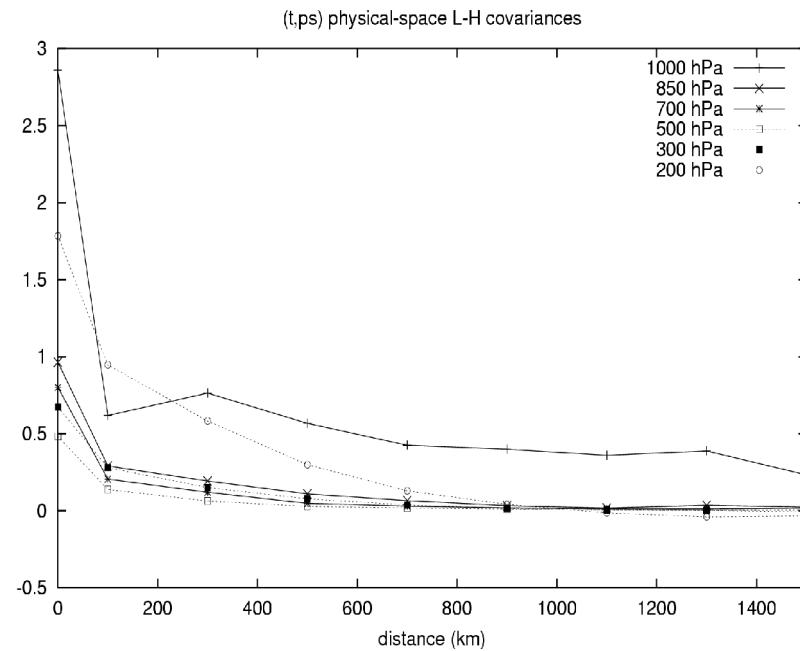


# Background errors

## 1. Innovation (Lönnberg - Hollingsworth) diagnostics

$$\epsilon_b = y - H(x_b) \longrightarrow \text{corr}(\epsilon_b, \epsilon_b)$$

- derive correlation function by averaging over similar distances
- extrapolation of the correlation function to 0 distance
- only std. dev. were revised



## 2. Ensemble method

$$\epsilon_b = M_{6h}(x_{al}) - M_{6h}(x_{a2})$$

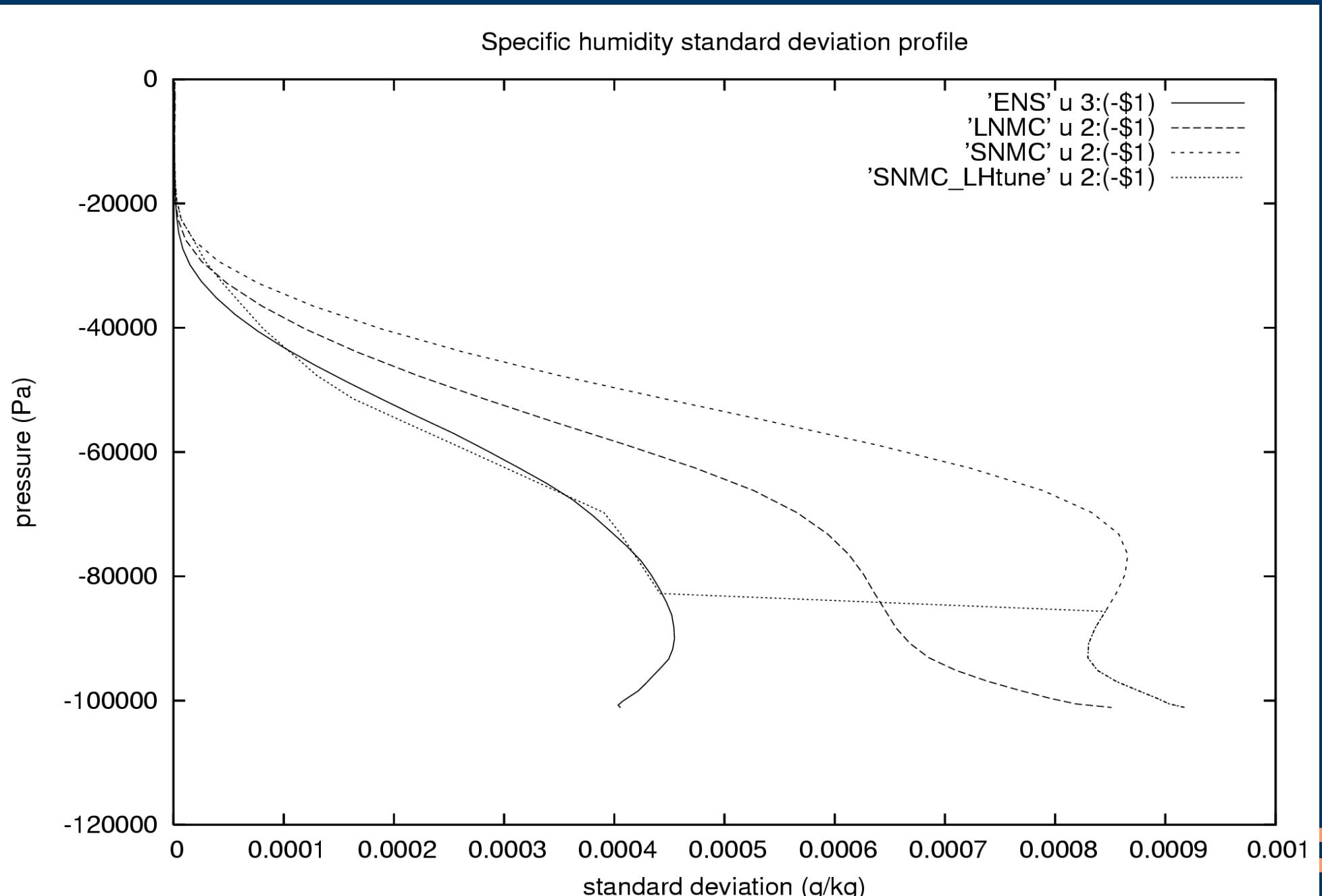
$$x_{al} = x_{al}(y_1)$$

$$x_{a2} = x_{al}(y_2)$$

$y_1, y_2$  : perturbed observations

- perturbations in ARPEGE
- downscaling to ALADIN/HU
- the full B matrix is recomputed

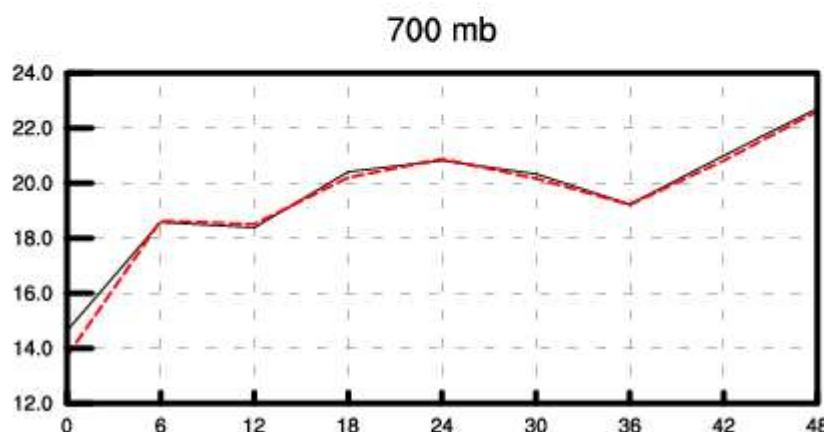
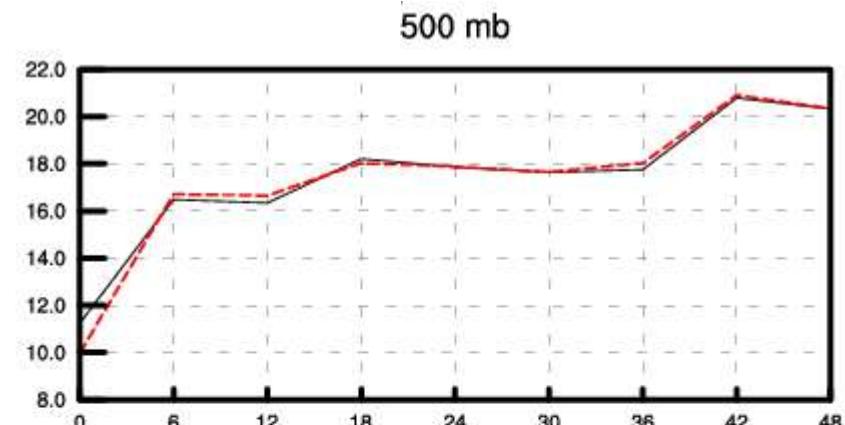
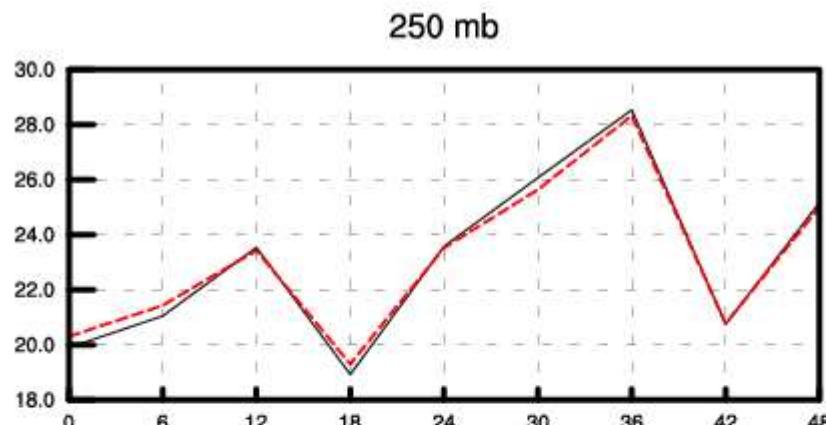
# Background errors



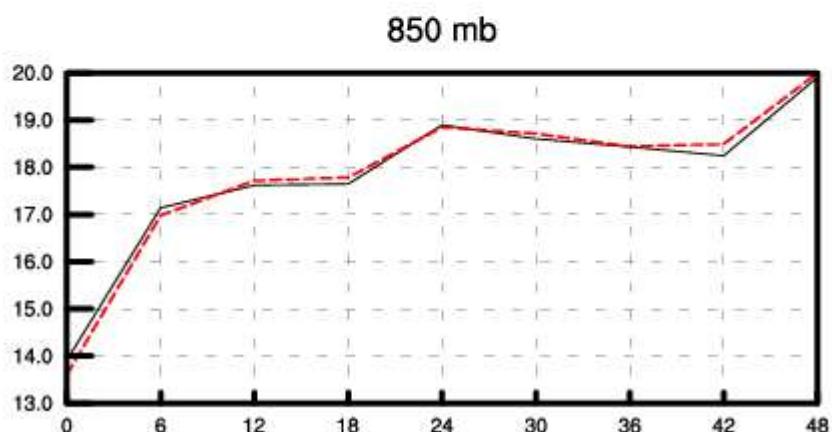
# *Background errors*

NMC with Lönnberg - Hollingsworth tuning

humidity RMSE

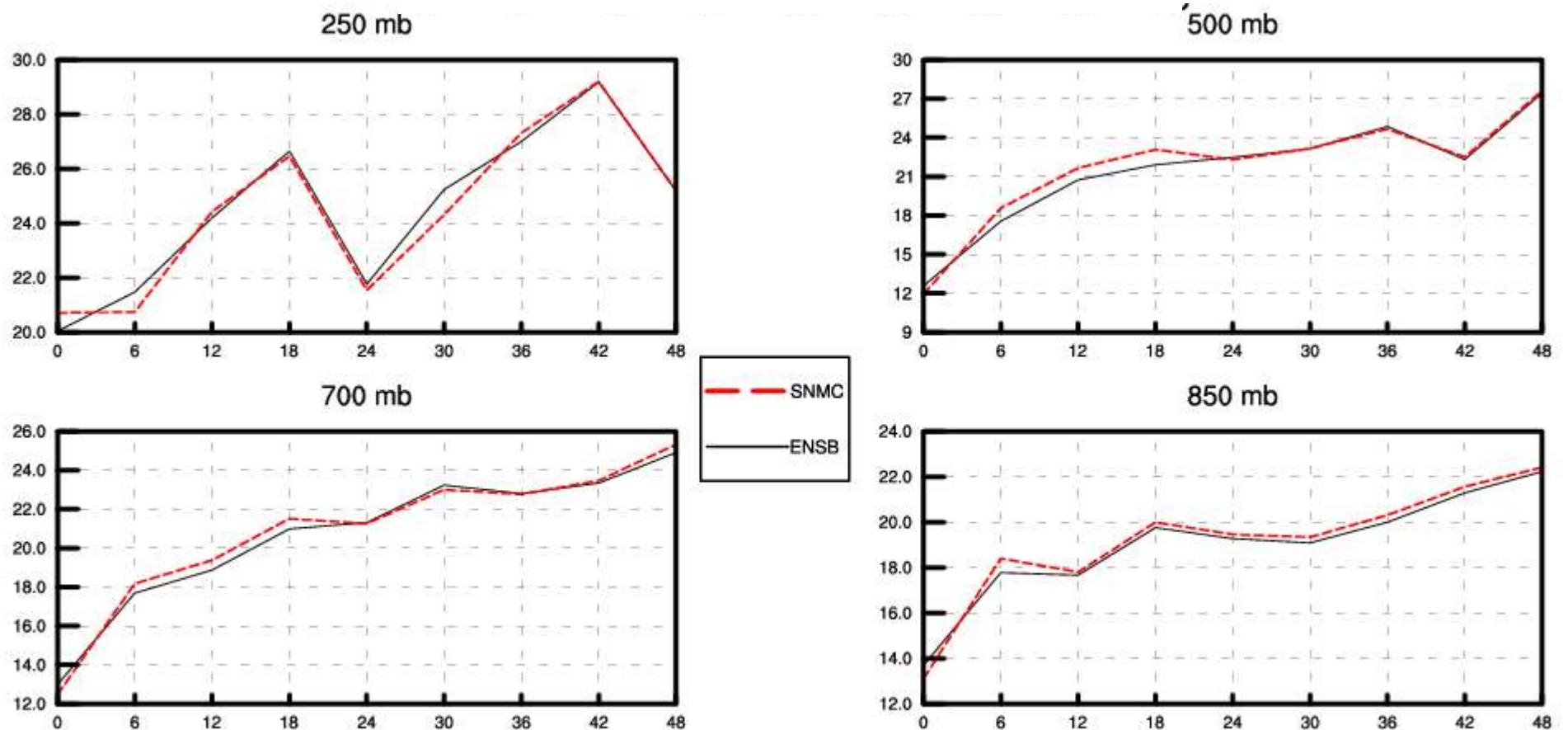


REFQ  
EX3Q



# *Background errors*

Ensemble method  
humidity RMSE

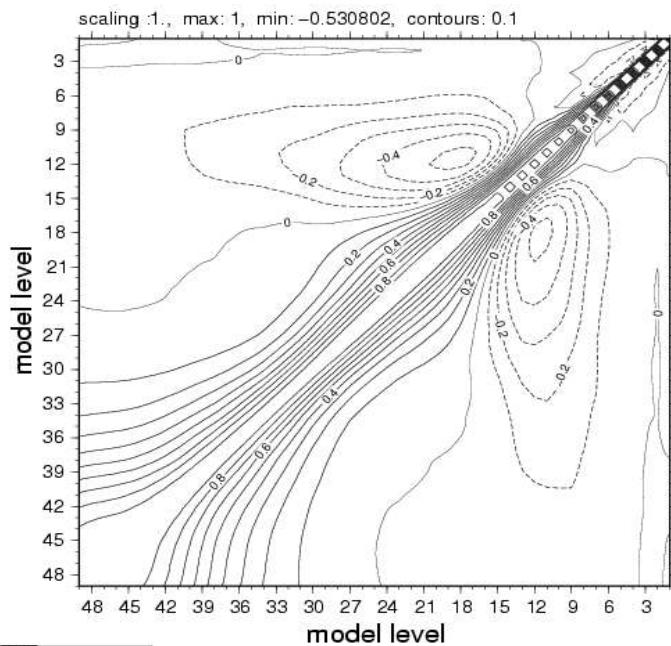


# Background errors

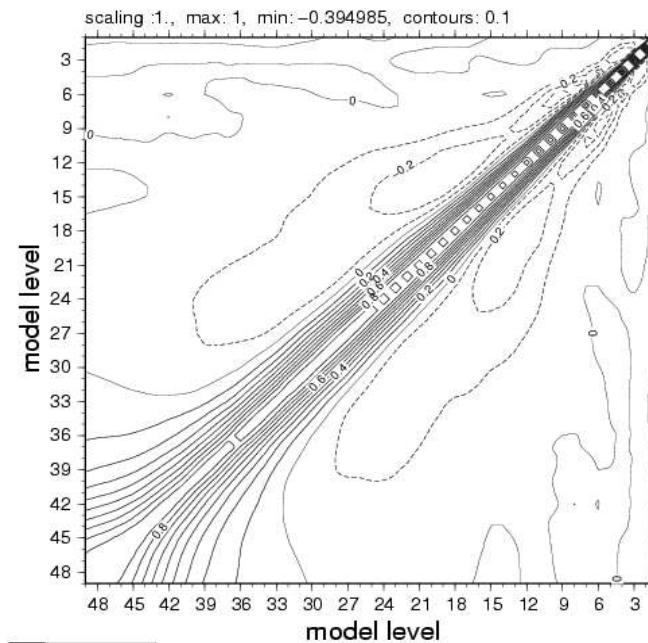
Ensemble method: other diagnostics

temperature vertical  
correlations

SNMC



Ensemble



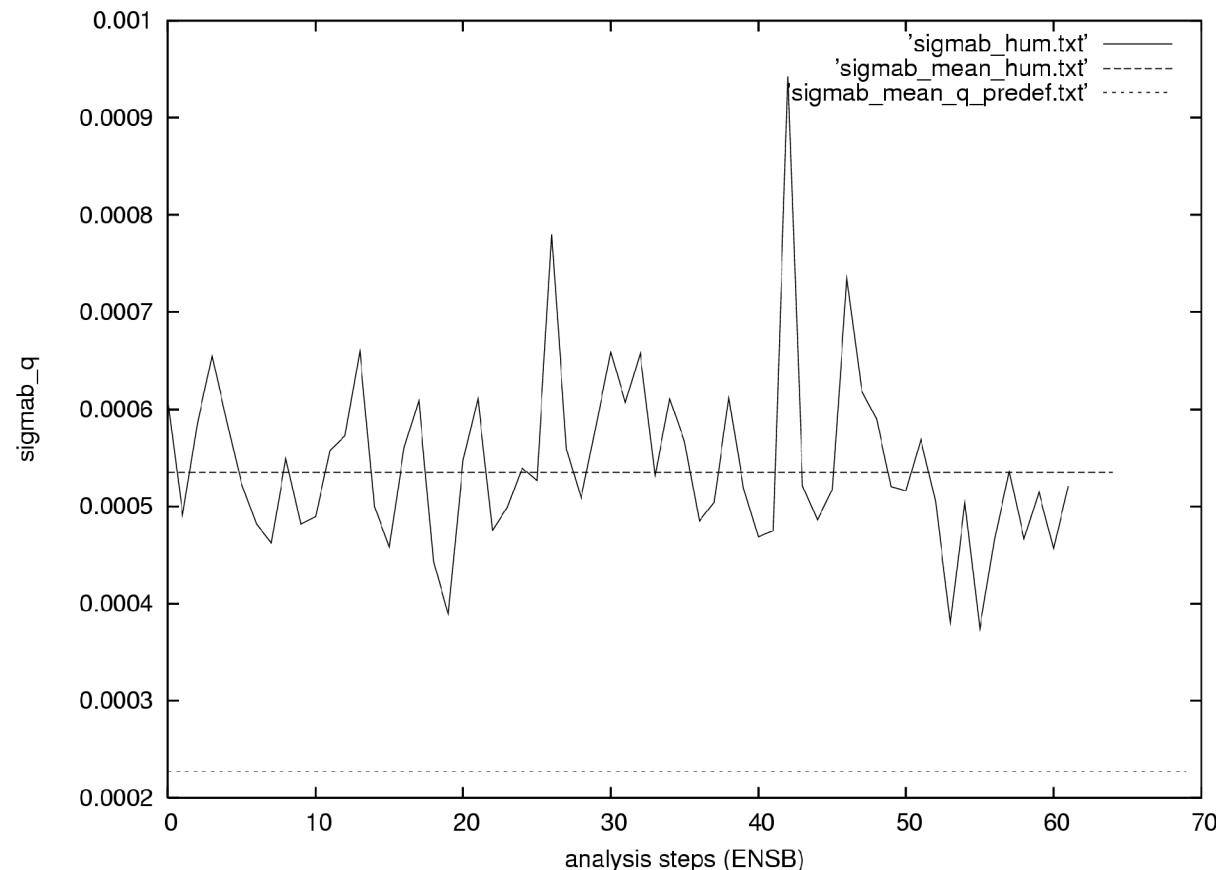
# Background errors

## A posteriori diagnosis

$$\hat{\sigma}_b^2 = \frac{1}{P} \sum (H_i(x_b) - H_i(x_a))(y_i - H_i(x_b))$$

$$\hat{\sigma}_o^2 = \frac{1}{P} \sum (y_i - H_i(x_a))(y_i - H_i(x_b))$$

Desroziers et al. (2005)

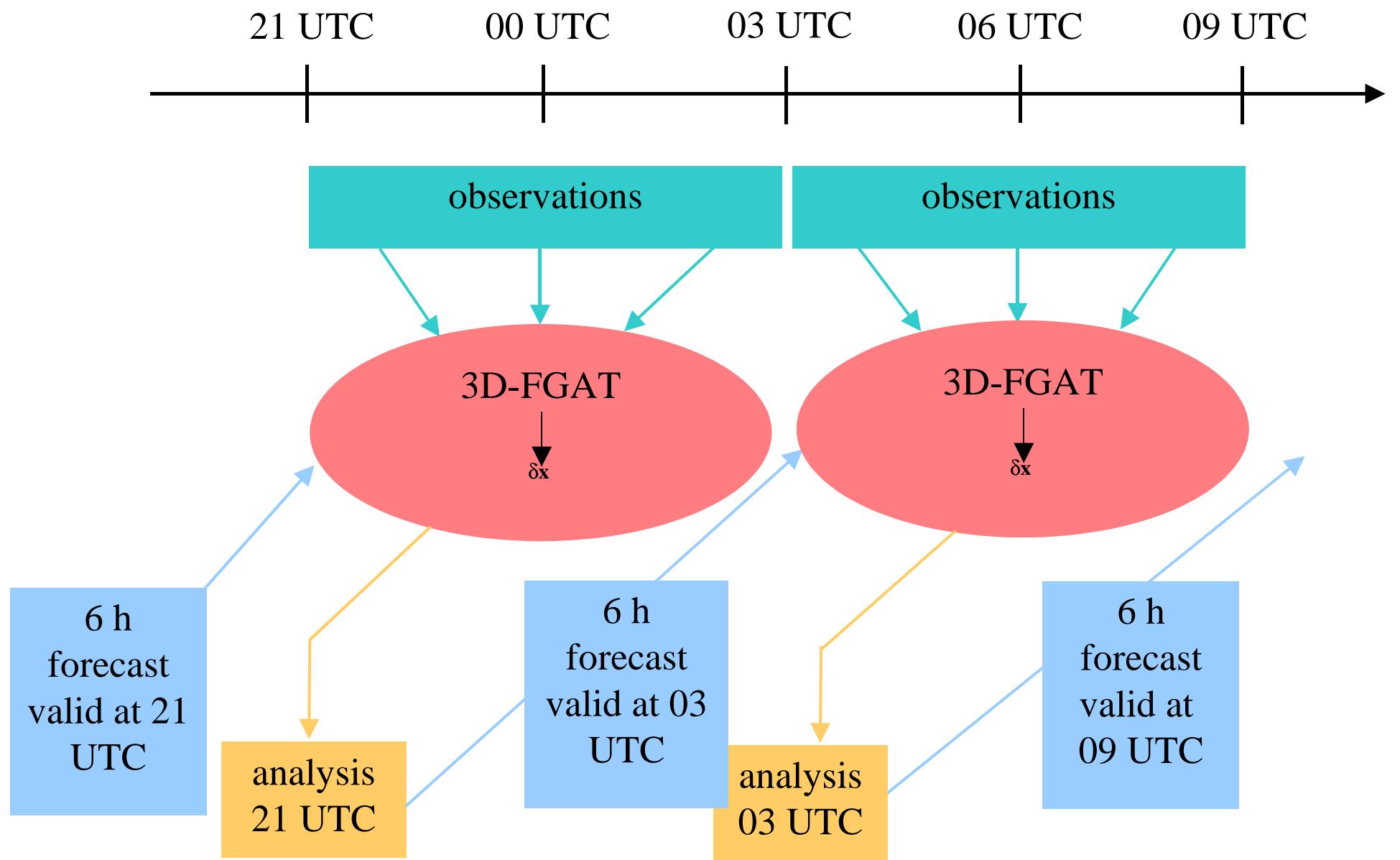


# **3D-FGAT**

## First experiments

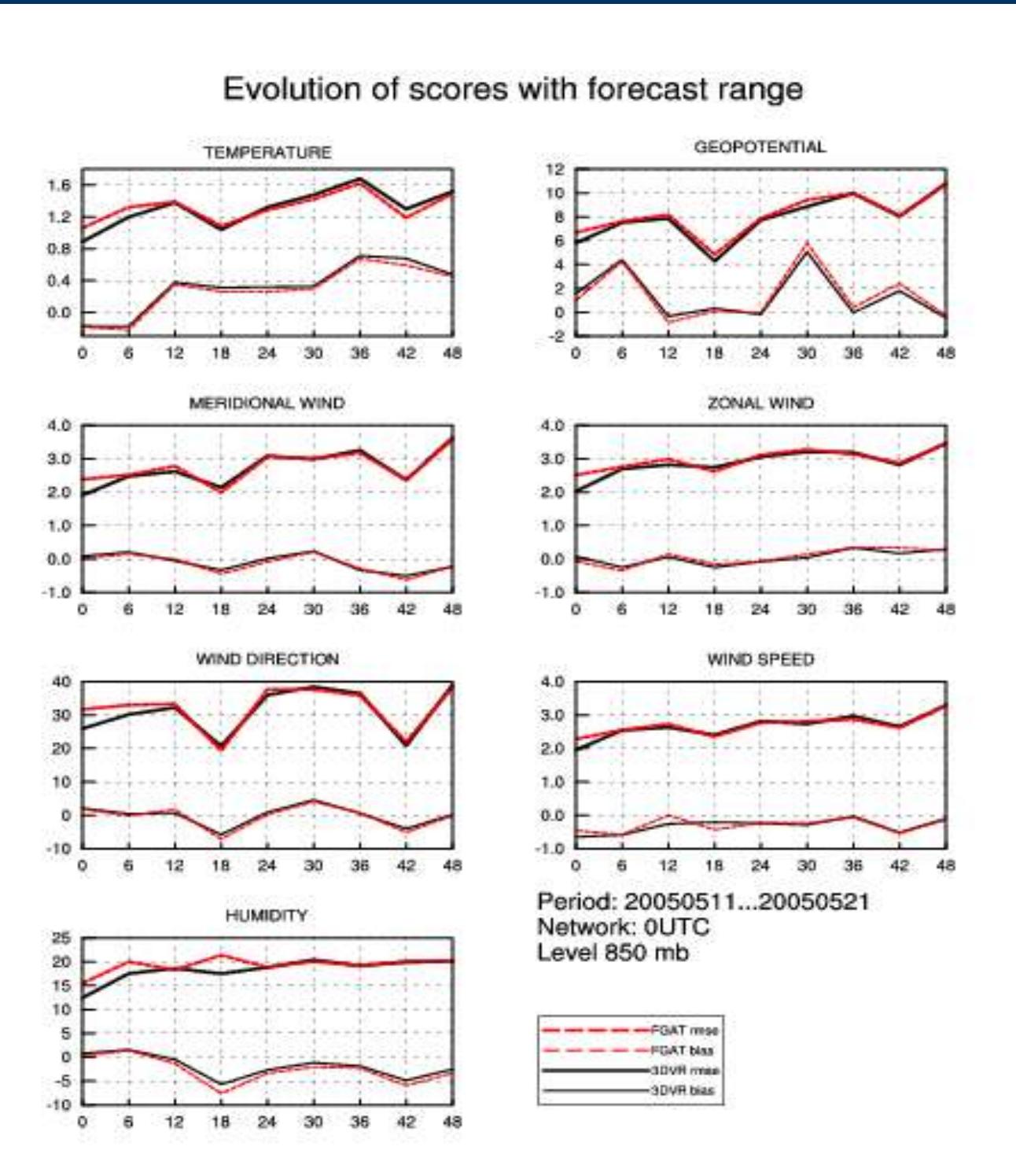
1. single observation experiments (comparison with 3DVAR)
2. Assimilation cycle for 10 days (10 – 20 May, 2005)
  - Former ALADIN/LACE domain ( $dx=12\text{km}$ , 37 levels)
  - As many observations as possible:
    - SYNOP, TEMP, Wind profilers
    - AMDAR, MSG/AMV, AMSU-A,
    - AMSU-B
  - comparison with an “equivalent” 3DVAR cycle

# 3D-FGAT



# 3D-FGAT

3DVAR  
analysis ~ 3h forecast  
48h forecast ~ 51h forecast



# *Observations*

- AMSU-B parallel suite
- AMV experiments
- EUCOS experiments



# *Observations*

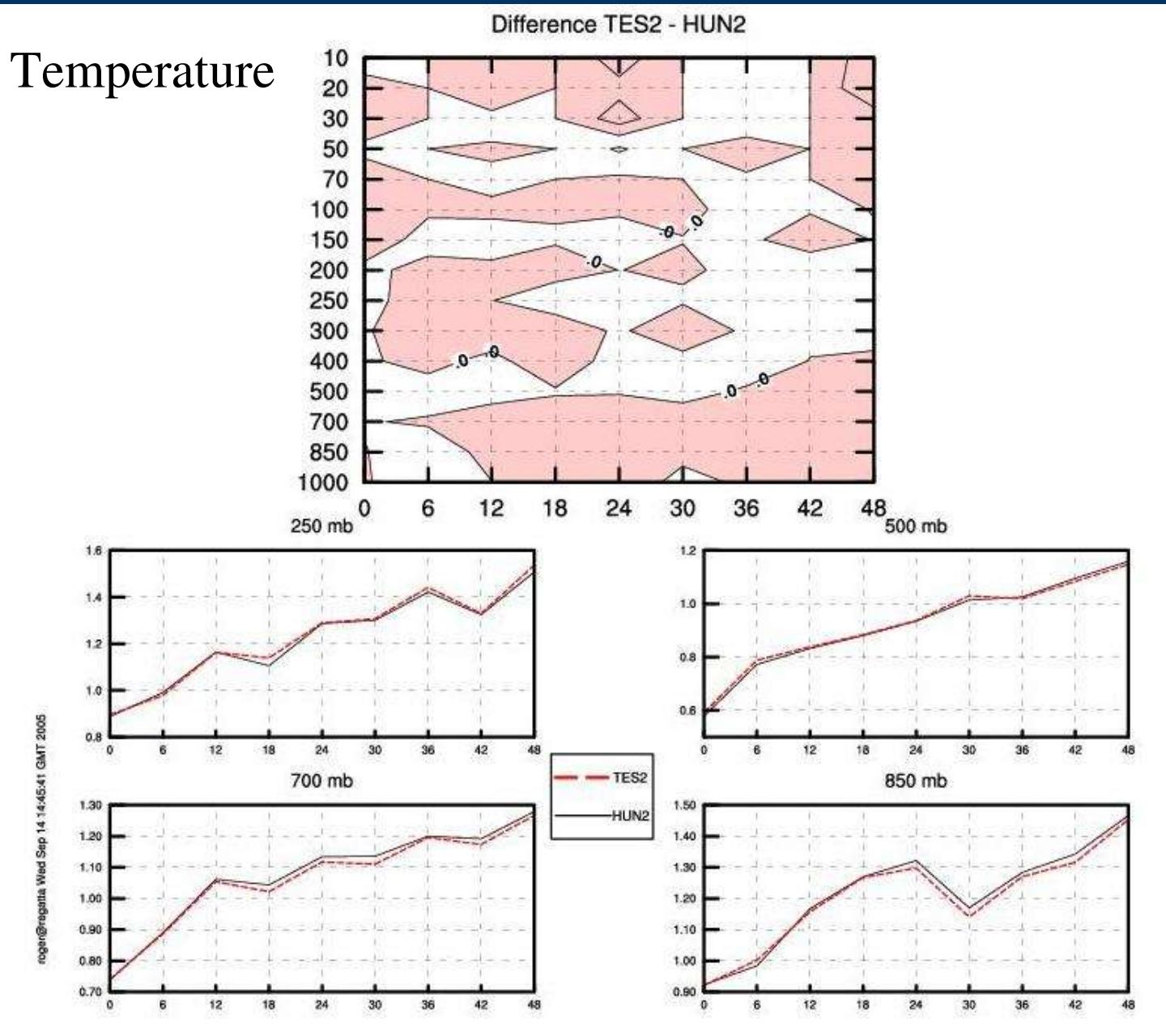
## AMSU-B parallel suite

- same setup as the operational + ATOVS/AMSU-B observations
- NOAA 16 and 17
- data are used in full resolution
- objective scores
- daily subjective evaluation
- operational use (AMSU-B) since 01/02/2006

# Observations

AMSU-B (TES2)

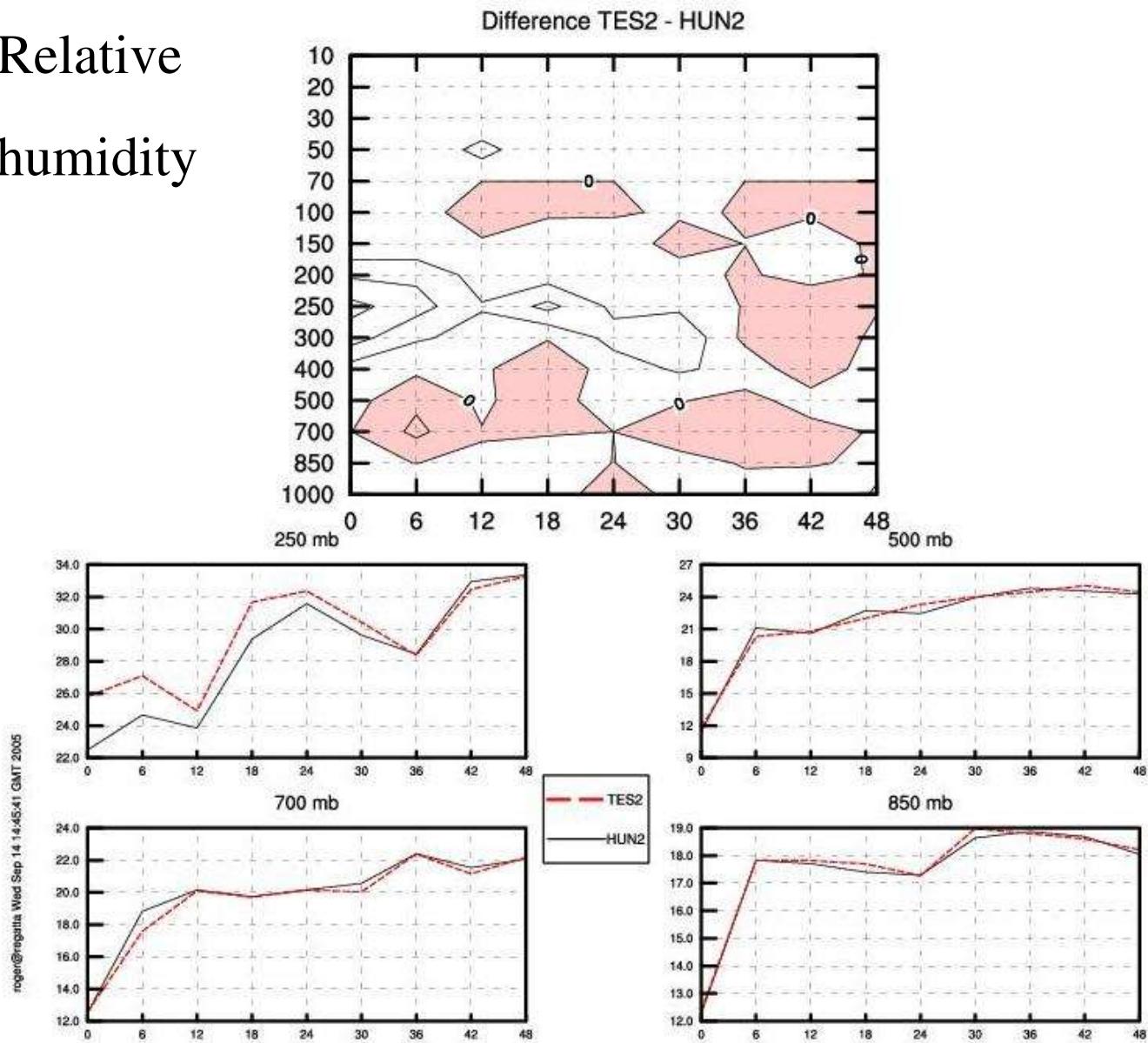
Temperature



# Observations

AMSU-B (TES2)

Relative  
humidity

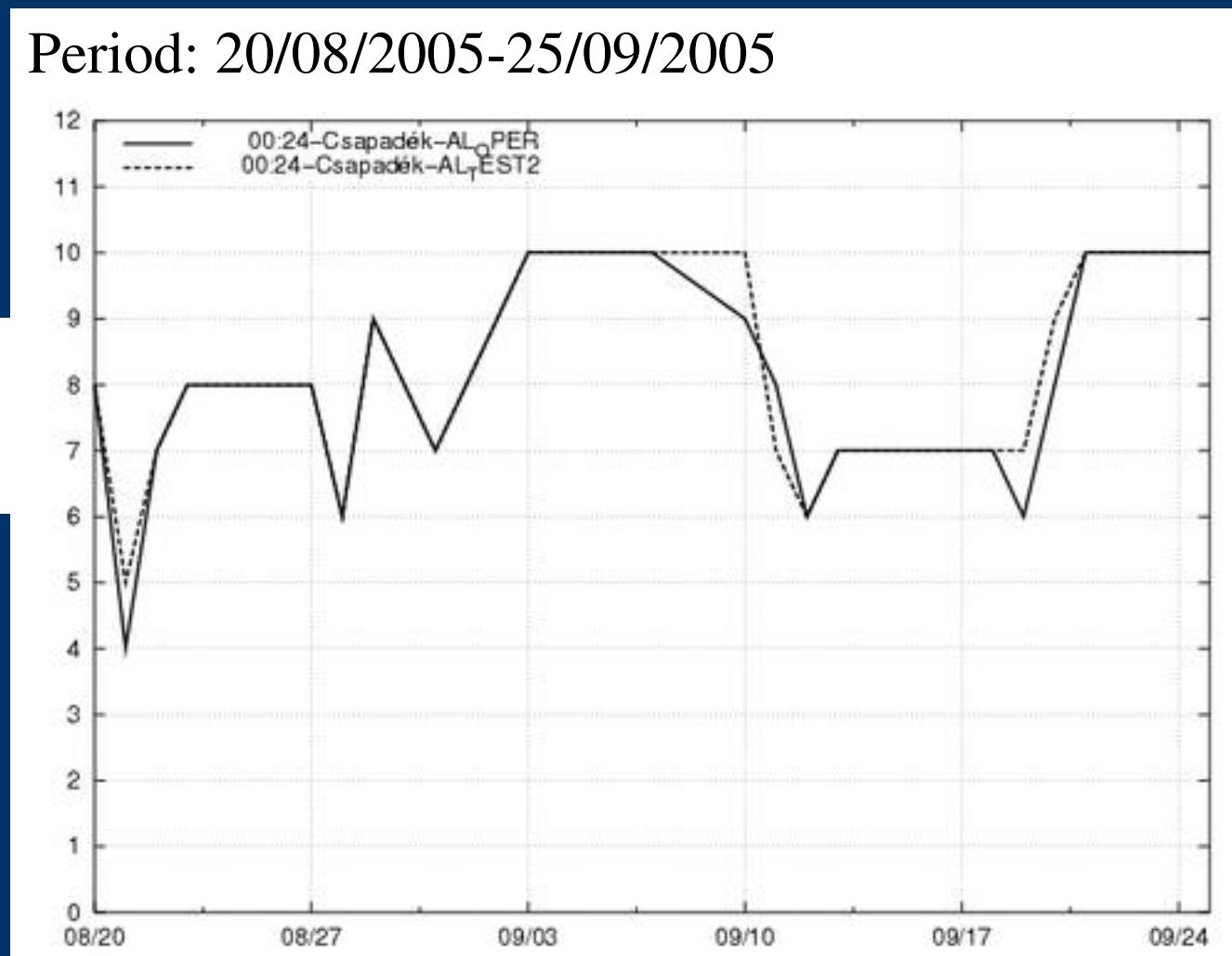


# Observations

AMSU-B

Period: 20/08/2005-25/09/2005

Precipitation  
0-24h

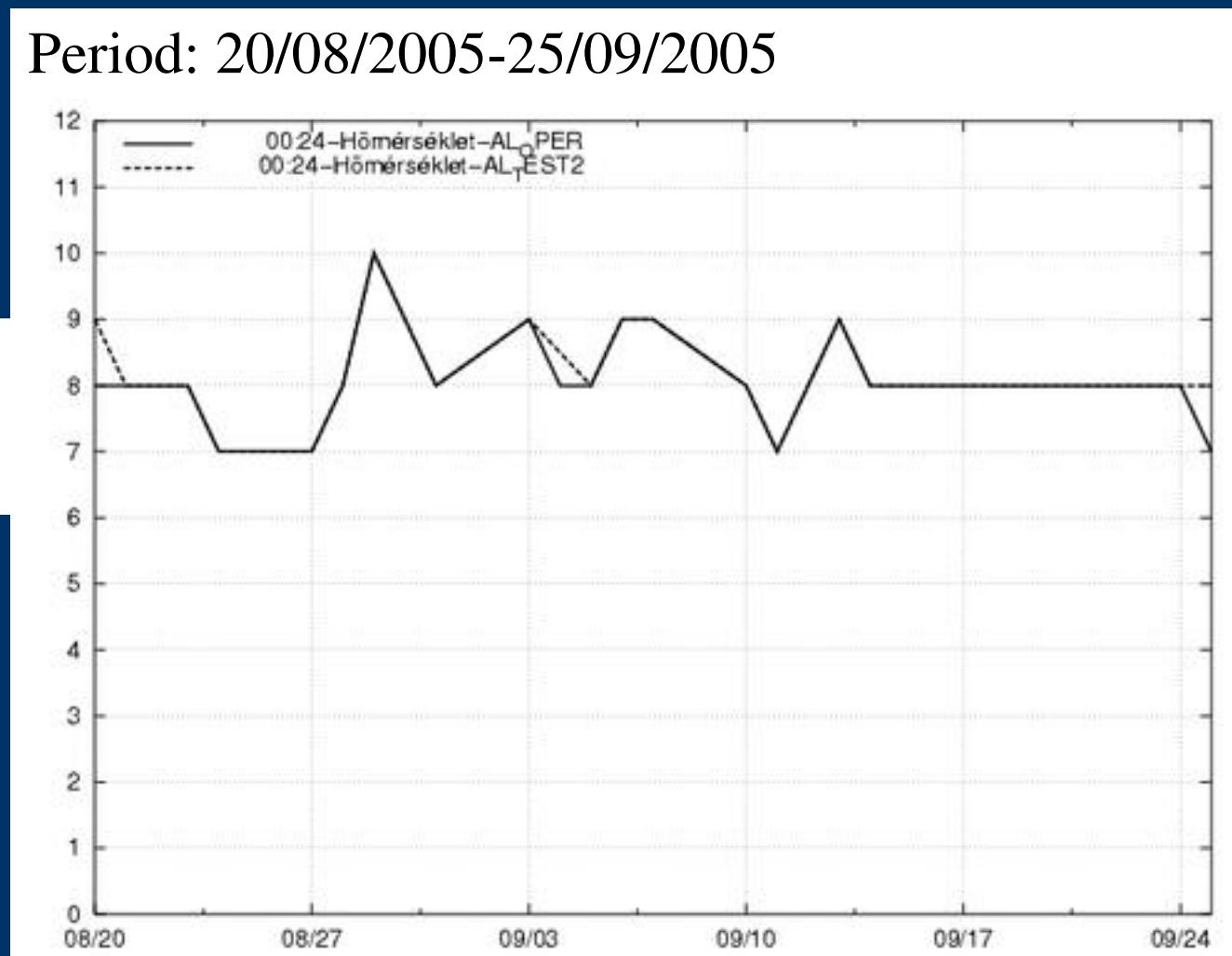


# Observations

AMSU-B

Period: 20/08/2005-25/09/2005

Temperature  
0-24h



# *Observations*

## AMV data

- METEOSAT-8 (MSG) data
- 3 ranges: HRV, IR, HWV
- u,v velocities

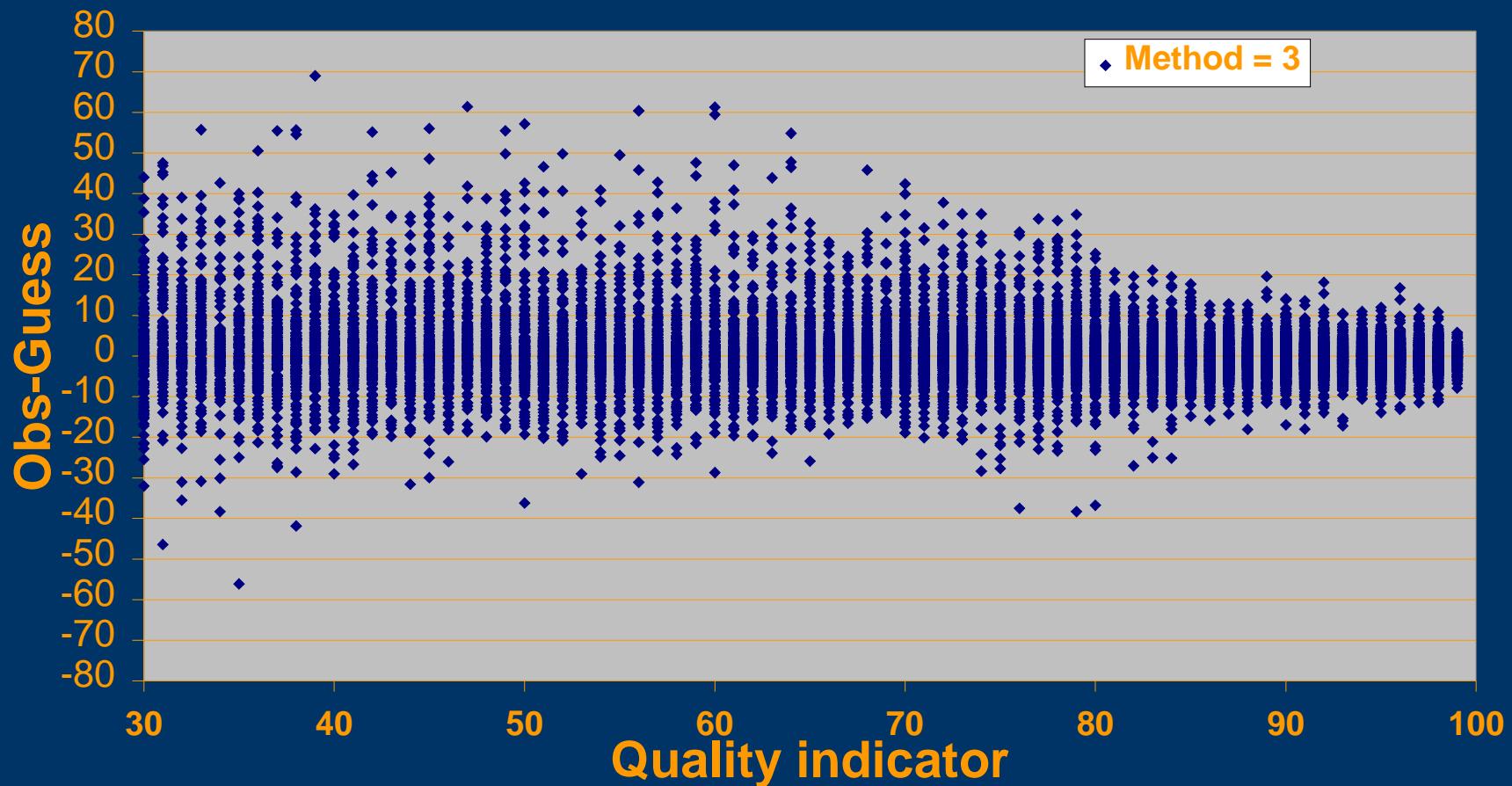
## Experiments

- impact studies: quality index, over sea/land
- objective scores, few cases

# Observations

AMV

V component  
Cloudy water vapor channels



# *Observations*

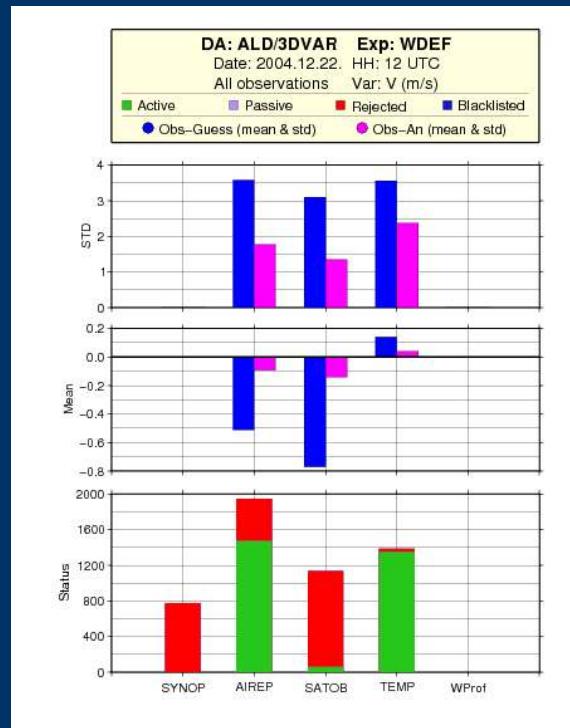
## Experiments

	QI	use over land
WDEF	QI > 85%	no
W80P	QI > 80%	no
WLAN	QI > 85%	yes

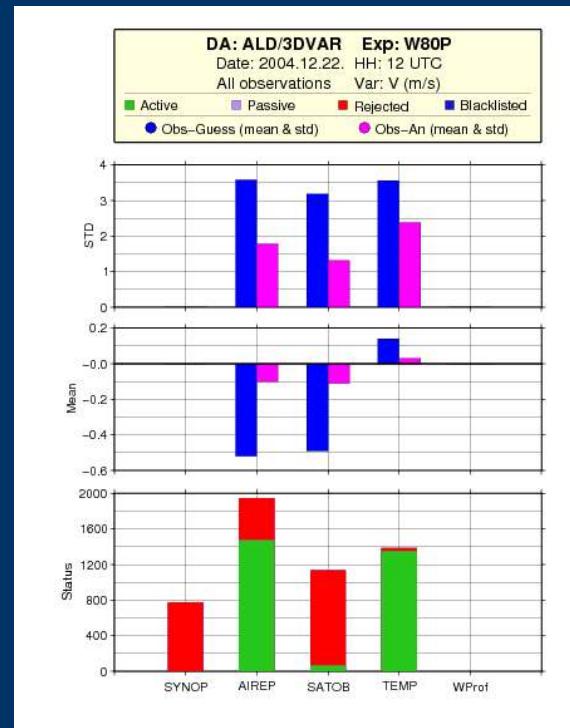
$350 \text{ hPa} < p < 800 \text{ hPa}$  → data are not used

# Observations

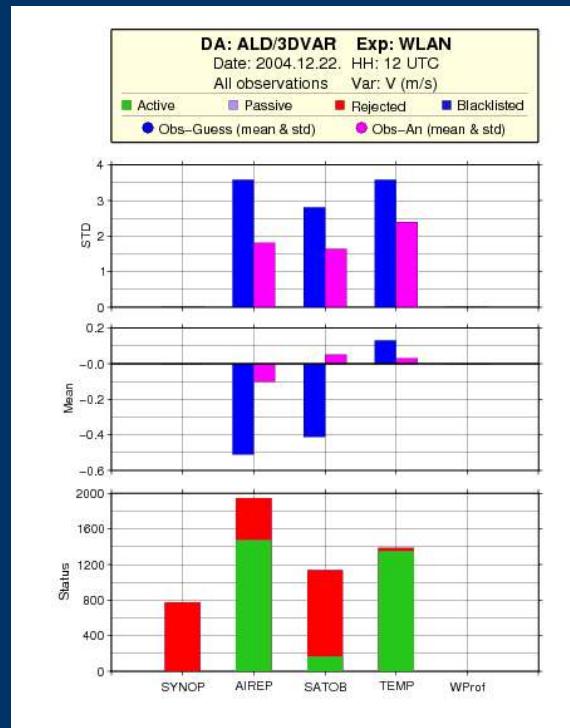
WDEF



W80P



WLan

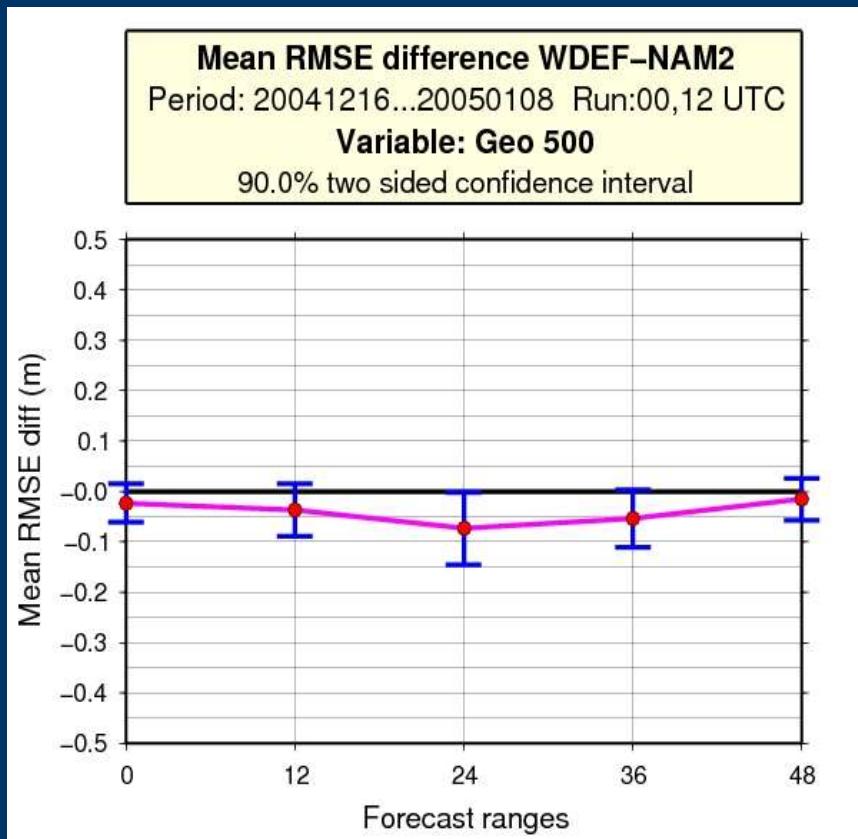


Active AMV : 57

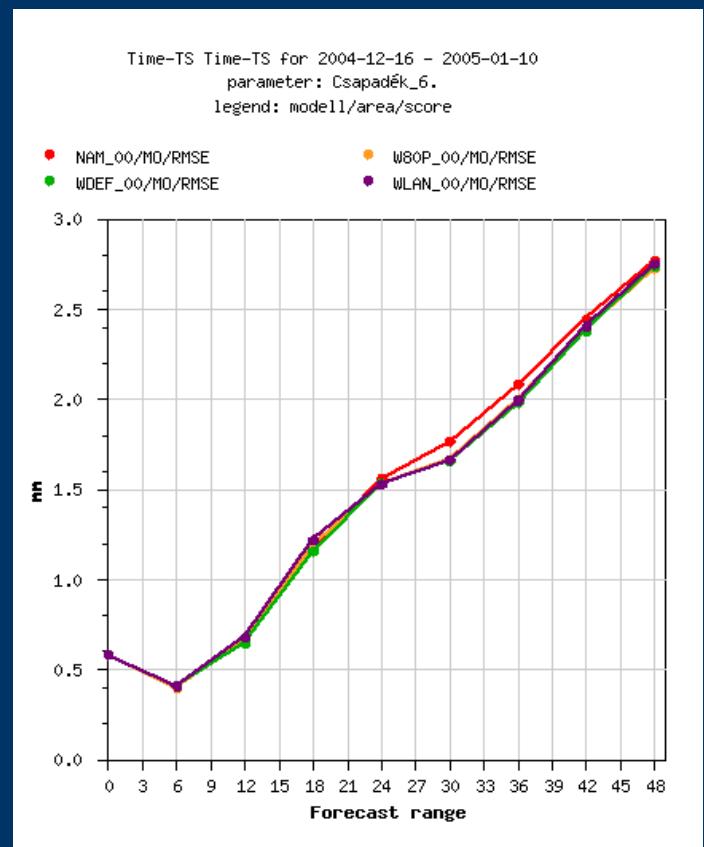
69

165

# Observations



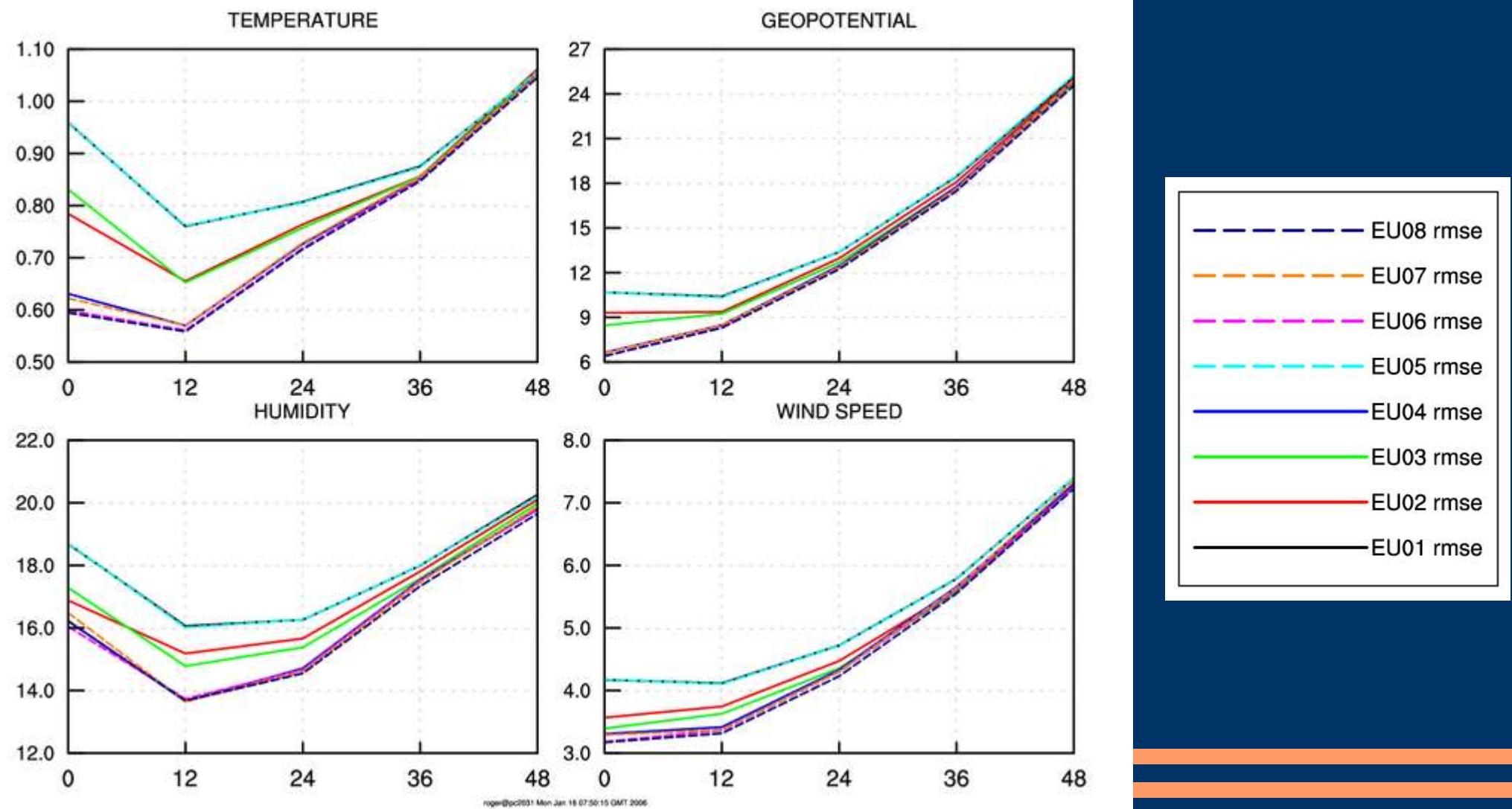
RMSE diff with significance test



Precipitation RMSE (Hungary)

# Observations

EUCOS: impact of the ground based observing system



# *Plans*

## Error statistics

- a posteriori diagnostics and tuning (continuation)
- ensemble B matrix
- compute/implement grid-point sigmab maps

## 3D-FGAT

- add the analysis increment at the middle of the window
- further experiments

## Observations

- EUCOS (continuation)
- RH2m and T2m from SYNOP
- SEVIRI data

## Operations

- cy30
  - move to SGI Altix
  - 4 productions/day (new assimilation script structure)
- 
-

*Thanks for your attention!*

