



Scale-dependent parametrization of orographic momentum fluxes in HIRLAM

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FINNISH METEOROLOGICAL INSTITUTE



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HIRLAM problems







HIRLAM problems

• Always windy





HIRLAM problems

- Always windy
- Pressure bias





HIRLAM problems

- Always windy
- Pressure bias
- \Rightarrow More drag to the model



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HIRLAM problems

- Always windy
- Pressure bias
- \Rightarrow More drag to the model
- Gravity wave drag

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HIRLAM problems

- Always windy
- Pressure bias
- \Rightarrow More drag to the model
- Gravity wave drag
- Modifying surface drag



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HIRLAM problems

- Always windy
- Pressure bias
- \Rightarrow More drag to the model
- Gravity wave drag
- Modifying surface drag
- \Rightarrow Modifying turbulent mixing









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Tendencies of the horizontal wind $\vec{v}(x, y, z)$ - explicitly resolved and parametrized:





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$$\frac{\partial \vec{v}}{\partial t} = (\frac{\partial \vec{v}}{\partial t})_d + (\frac{\partial \vec{v}}{\partial t})_p$$





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Parametrized tendency is due to the divergence of the stress tensor τ_{ij}





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Parametrized tendency is due to the divergence of the stress tensor τ_{ij}

$$(rac{\partial ec{v}}{\partial t})_p = rac{1}{
ho} rac{\partial ec{ au}}{\partial z}, ec{ au} = -\sum_{j=1}^n
ho(\overline{ec{v}'w'})$$



Several sub-grid scales of orography





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 \blacktriangleright

Components of the parametrized drag

| drag | related to | momentum sink | scale |
|---|---|--|--|
| $egin{array}{c} ec{	au}_{ts} & ec{	au}_{o} & ec{	au}_{m} & ec{	au}_{w} & ec{	au}_{t} & e$ | turbulent drag due to surface roughness drag due to unresolved small-scale orography blocked flow drag due to mesoscale orography drag due to breaking buoyancy waves turbulence (vertical diffusion) | surface (2D) internal (3D) internal (3D) internal (3D) internal (3D) | micro small meso meso < Δx |
| | | | |
| | | | |









Phenomena related to buoyancy waves: wave breaking, blocking





Phenomena related to buoyancy waves: wave breaking, blocking Wave parametrizations from Lilly (1972), Boer et al. (1984) ...



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+ wave breaking at saturation level, reflection



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* blocked flow drag = form drag according to Lott and Miller







Effective or orographic roughness approach - Mason (1985) ...



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Small scale orography (SSO) parametrizations

Effective or orographic roughness approach - Mason (1985) ... Problems of this approach:



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Effective or orographic roughness approach - Mason (1985) ... Problems of this approach:

- all scales included



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Effective or orographic roughness approach - Mason (1985) ... Problems of this approach:

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- indirect: height variance + slopes \Rightarrow z_{0,oro}



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Small scale orography (SSO) parametrizations

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- 3d effects flattened to surface



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- SSO directly influence $\left(\frac{\partial \vec{v}}{\partial t}\right)_p$
- stability effects included via u_*
- three-dimensionality by exp(-z/l)



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In HIRLAM: z_{oro} used, alternative approach tested



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Orography parameters and scales

| variable | definition | scale of orograph |
|--------------------------|---|-------------------|
| | For resolved dynamics | |
| $\mathbf{H}_{2\Delta x}$ | mean height | > 2∆x |
| | For mesoscale orography parametrization | |
| σ_m | standard deviation of mesoscale orography | 3 km - 2∆x |
| α | anisotropy of the mesoscale orography | 3 km - 2∆x |
| θ | angle between mesoscale ridges and model's x-axis | 3 km - 2∆x |
| | For small-scale orographic stress | |
| (z _{0 oro} | orographic roughness | < 3 km) |
| S _t | averaged maximum slope s_{max} | < 3 km |
| σ_t | smallest scale standard deviation | < 3 km |
| | For turbulence over flat rough surface | |
| z_0 | roughness | << 1 km |
| Z 0 | roughness | << 1 km |



Source: digital elevation map





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Old experiments and verification pictures

experiment description

| RC33 | reference HIRLAM with technical corrections |
|------|--|
| NO33 | RC33 but SSO parametrization instead of z _{oro,0} |
| NM33 | NO33 but MSO parametrization added |
| NT33 | NM33 but with rotated turbulent stress vector |

European area with $\Delta x=33$ km/40 levels, 00 UTC only + 48h HIRLAM v.6.3.3, boundaries from 33 km/40 level HIRLAM reanalysis 6.2.2 run at ECMWF for the year 2000, observations from ECMWF archive.

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Station verification

against EWG observations RC33 (left) NO33 (right) Period: 20000119 - 20000129

Surface pressure

Two metre temperature







6 12 18 24 30 36 42 48

Forecast length (hours)

BIAS

RMS

Mean speed and RMS vector error (m/s)

0

-1

0

- BIAS

RMS











against EWG observations RC33 (left) NM33 (right) Period: 20000119 - 20000129

Surface pressure

Two metre temperature







Mean speed and RMS vector error (m/s)



Two metre relative humidity







against EWG observations RC33 (left) NT33 (right) Period: 20000119 - 20000129

Surface pressure

Two metre temperature





Ten metre wind



Two metre relative humidity





New experiments and verification pictures





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Integration areas of the 33 km (full area of the map) and 11 km (box outlined by dashed line) experiments. Shown in the figure are isolines of the surface elevation (whole area, isoline spacing 300 m) and mean sea level pressure averaged over January 2000 (small area, given by the +48h forecasts of the experiment O33, isoline spacing 5 hPa).





against Isl observations R33 (left) O33 (right) Period: 20000101 - 20000131



Two metre temperature







0 6 12 18 24 30 36 42 48

Forecast length (hours)

BIAS

RMS

Mean speed and RMS vector error (m/s)

2

0

-1

-2

-3

-1

- BIAS

--- RMS









against Isl observations R33 (left) BB33 (right) Period: 20000101 - 20000131

Surface pressure

Two metre temperature







Mean speed and RMS vector error (m/s)



Two metre relative humidity





More verification pictures, with explanations

Mean sea level pressure

Mean sea level pressure

Mean sea level pressure



Experiments from left to right: R33, O33, B33.



Lowest model level wind speed January 2000 00UTC+48h





R33=Reference experiment, O33=MSO+Hirlam style SSO, B33=MSO+ECMWF style SSO. Unit: m/s, area: Iceland.



Total surface stress, January 2000 00UTC+48h





Summary and conclusions



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Summary and conclusion



Summary and conclusions

• Parametrizations of orography-related momentum fluxes in HIRLAM were renewed by replacing the effective roughness approach by new meso- and small-scale orography parametrizations.





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Summary and conclusions

Parametrizations of orography-related momentum fluxes
in HIRLAM were renewed by replacing the effective roughness
approach by new meso- and small-scale orography parametrizations.
The needed scale-dependent orography variables were derived
from high-resolution digital elevation map.



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 Parametrization schemes representing different sub-grid scales interact and partly compensate each other.
 New parametrizations increase the total drag only a little.





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from high-resolution digital elevation map.
Parametrization schemes representing different sub-grid

scales interact and partly compensate each other. New parametrizations increase the total drag only a little.

• Careful verification and use of diagnostic tools to analyse kinetic energy and vorticity budget are needed to understand the effects and interactions of the parametrizations.



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